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## THB6016H

### PWM Chopper-Type bipolar Stepping Motor Driver IC

The THB6016H is a PWM chopper-type sinusoidal micro-step bipolar stepping motor driver IC.

It supports both 2-phase/1-2-phase/2W1-2-phase /4W1-2-phase excitation mode and forward/reverse mode and is capable of low-vibration, high-performance drive of 2-phase bipolar type stepping motors using only a clock signal.

#### Features

Single-chip bipolar sinusoidal micro-step stepping motor driver

Uses high withstand voltage BiCD process:

$R_{on}$  (upper + lower) = 0.60 (typ.)

Forward and reverse rotation control available

Selectable phase drive (2, 1-2, W1-2, and 2W1-2)

High output withstand voltage:  $V_{CEO} = 40\text{ V}$

High output current:  $I_{OUT} = \text{HQ: } 3.5\text{ A (peak)}$

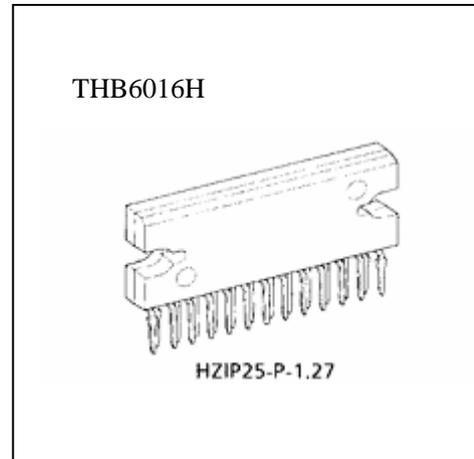
Packages: HZIP25-P-1.27

Built-in input pull-down resistor: 100k (typ.)

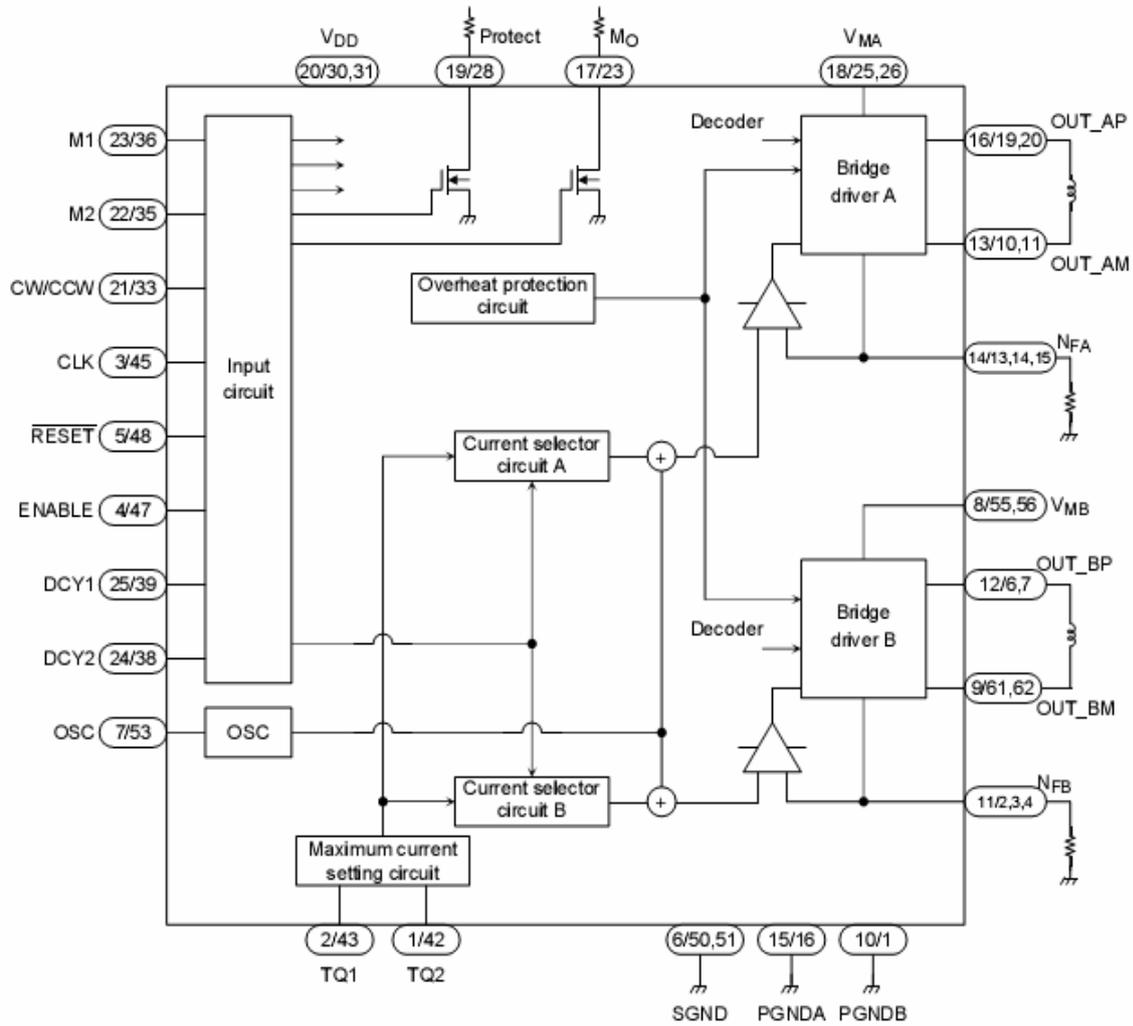
Output monitor pin equipped: MO current ( $I_{MO}$  (max)) = 1 mA

Equipped with reset and enable pins

Built-in overheat protection circuit



Block Diagram



THB6016H

Pin Functions

Pin No.		I/O	Symbol	Functional Description
HQ	FG			
1	42	Input	TQ2	Torque setting input (current setting) (built-in pull-down resistor)
2	43	Input	TQ1	Torque setting input (current setting) (built-in pull-down resistor)
3	45	Input	CLK	Step transition, clock input (built-in pull-down resistor)
4	47	Input	ENABLE	H: Enable; L: All output OFF (built-in pull-down resistor)
5	48	Input	RESET	L: Reset (output is reset to its initial state) (built-in pull-down resistor)
6	50/51	—	SGND	Signal ground (control side) (note:1)
7	53	—	OSC	Connects to and oscillates CR. Output chopping.
8	55/56	Input	V <sub>MB</sub>	Motor side power pin (B phase side) (note:1)
9	61/62	Output	OUT <sub>BM</sub>	OUT <sub>B</sub> output (note:1)
10	1	—	PGNDB	Power ground (note:1)
11	2/3/4	—	N <sub>FB</sub>	B channel output current detection pin (resistor connection). Short the two pins for FG. (note:1)
12	6/7	Output	OUT <sub>BP</sub>	OUT <sub>B</sub> output (note:1)
13	10/11	Output	OUT <sub>AM</sub>	OUT <sub>A</sub> output (note:1)
14	13/14/15	—	N <sub>FA</sub>	A channel output current detection pin (resistor connection). Short the two pins for FG. (note:1)
15	16	—	PGNDA	Power ground
16	19/20	Output	OUT <sub>AP</sub>	OUT <sub>A</sub> output (note:1)
17	23	Output	M <sub>O</sub>	Initial state detection output. ON when in initial state (open drain).
18	25/26	Input	V <sub>MA</sub>	Motor side power pin (A phase side) (note:1)
19	28	Output	Protect	When TSD, ON (open drain). Normal Z.
20	30/31	Input	V <sub>DD</sub>	Control side power pin. (note:1)
21	33	Input	CW/CCW	Forward/Reverse toggle pin. L: Forward; H: Reverse (built-in pull-down resistor)
22	35	Input	M <sub>2</sub>	Excitation mode setting input (built-in pull-down resistor)
23	36	Input	M <sub>1</sub>	Excitation mode setting input (built-in pull-down resistor)
24	38	Input	DCY <sub>2</sub>	Current Decay mode setting input (built-in pull-down resistor)
25	39	Input	DCY <sub>1</sub>	Current Decay mode setting input (built-in pull-down resistor)

H: No NC

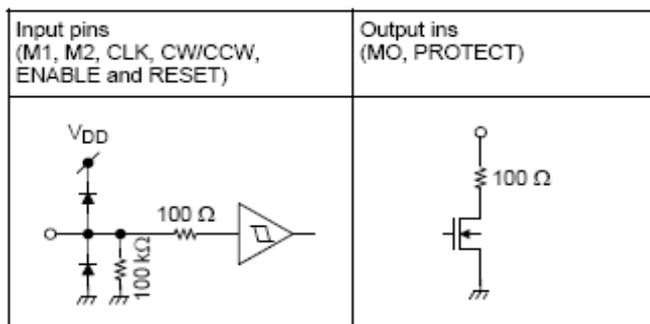
F: Other than the above pins, all are NC

Pull-down resistor 100 k (typ.): [all control input pins]

Note:1--- - If the F pin number column indicates more than one pin, the indicated pins should be tied to each other at a position as close to the pins as possible.

(The electrical characteristics of the relevant pins in this document refer to those when they are handled in that way.)

<Terminal circuits>



**Absolute Maximum Ratings (Ta = 25°C)**

Characteristic		Symbol	Rating	Unit
Power supply voltage		V <sub>DD</sub>	6	V
		V <sub>MA/B</sub>	40	
Output current	Peak	I <sub>O (PEAK)</sub>	3.5	A/phase
	HQ		2.5	
	FG			
MO drain current		I <sub>(MO)</sub>	1	mA
Input voltage		V <sub>IN</sub>	5.5	V
Power dissipation		P <sub>D</sub>	5 (Note 1)	W
			43 (Note 2)	
			1.7 (Note 3)	
			4.2 (Note 4)	
	HQ			
	FG			
Operating temperature		T <sub>opr</sub>	-30 to 85	°C
Storage temperature		T <sub>stg</sub>	-55 to 150	°C

Note 1: Ta = 25°C, No heat sink.

Note 2: Ta = 25°C, with infinite heat sink (HZIP25).

Note 3: Ta = 25°C, with soldered leads.

Note 4: Ta = 25°C, when mounted on the board (4-layer board).

Susceptible to the board layout and the mounting conditions.

**Operating Range (Ta = -30 to 85°C)**

Characteristic		Symbol	Test Condition	Min	Typ.	Max	Unit
Power supply voltage		V <sub>DD</sub>	—	4.5	5.0	5.5	V
		V <sub>MA/B</sub>	V <sub>MA/B</sub> ≥ V <sub>DD</sub>	4.5	—	(34)	V
Output current	HQ	I <sub>OUT</sub>	—	—	—	3	A
	FG					1.5	
Input voltage		V <sub>IN</sub>	—	0	—	5.5	V
Clock frequency		f <sub>CLK</sub>	—	—	—	15	kHz
OSC frequency		f <sub>OSC</sub>	—	—	—	600	kHz

**Electrical Characteristics (Ta = 25°C, VDD = 5 V, VM = 24 V)**

Characteristic	Symbol	Test Circuit	Test Condition	Min	Typ.	Max	Unit
Input voltage	High	V <sub>IN (H)</sub>	M1, M2, CW/CCW, CLK, $\overline{\text{RESET}}$ , ENABLE, DECAY, TQ1, TQ2, ISD	2.0	—	V <sub>DD</sub>	V
	Low	V <sub>IN (L)</sub>		-0.2	—	0.8	
Input hysteresis voltage	V <sub>H</sub>	1		—	400	—	mV
Input current	I <sub>IN (H)</sub>	1	M1, M2, CW/CCW, CLK, $\overline{\text{RESET}}$ , ENABLE, DECAY, TQ1, TQ2, ISD V <sub>IN</sub> = 5.0 V Built-in pull-down resistor	30	55	80	μA
	I <sub>IN (L)</sub>		V <sub>IN</sub> = 0 V	—	—	1	
Consumption current V <sub>DD</sub> pin	I <sub>DD1</sub>	1	Output open, RESET : H, ENABLE: H (2, 1-2 phase excitation)	—	3	5	mA
	I <sub>DD2</sub>		Output open, RESET : H, ENABLE: H (W1-2, 2W1-2 phase excitation)	—	3	5	
	I <sub>DD3</sub>		$\overline{\text{RESET}}$ : L, ENABLE: L	—	2	5	
	I <sub>DD4</sub>		RESET : H, ENABLE: L	—	2	5	
Consumption current V <sub>M</sub> pin	I <sub>M1</sub>	1	$\overline{\text{RESET}}$ : H/L, ENABLE: L	—	0.5	1	mA
	I <sub>M2</sub>		RESET : H/L, ENABLE: H	—	0.7	2	
Output channel margin of error	ΔV <sub>O</sub>	—	B/A, C <sub>OSC</sub> = 0.0033 μF	-5	—	5	%
VNF level Level differential	VNFHH	—	TQ1 = H, TQ2 = H	10	20	30	%
	VNFHL		TQ1 = L, TQ2 = H	47	50	55	
	VNFLH		TQ1 = H, TQ2 = L	70	75	80	
	VNFLL		TQ1 = L, TQ2 = L			100	
Minimum clock pulse width	t <sub>w</sub> (CLK)	—	C = 330 pF	—	7.7	—	μs
MO output residual voltage	V <sub>OL MO</sub>	—	I <sub>OL</sub> = 1 mA	—	—	0.5	V
TSD	TSD	—	(Design target value)	—	170	—	°C
TSD hysteresis	TSDhys	—	(Design target value)	—	20	—	°C
Oscillating frequency	f <sub>OSC</sub>	—	C = 330 pF	60	130	200	kHz

Electrical Characteristics (Ta = 25°C, VDD = 5 V, VM = 24 V)

Output Block

Characteristic		Symbol	Test Circuit	Test Condition	Min	Typ.	Max	Unit		
Output ON resistor	AHQ	Ron U1H	4	IOUT = 1.5 A	—	0.3	0.4	Ω		
		Ron L1H			—	0.3	0.4			
	AFG	Ron U1F		IOUT = 1.5 A	—	0.35	0.5			
		Ron L1F			—	0.35	0.5			
A-B chopping current (Note)	4W1-2-phase excitation	2W1-2-phase excitation	Vector	—	TQ1 = L, TQ2 = L	θ = 0	—	100	—	%
		—				θ = 1/16	—	100	—	
		2W1-2-phase excitation				θ = 2/16	93	98	100	
		—				θ = 3/16	91	96	100	
		2W1-2-phase excitation				θ = 4/16	87	92	97	
		—				θ = 5/16	83	88	93	
		2W1-2-phase excitation				θ = 6/16	78	83	88	
		—				θ = 7/16	72	77	82	
		2W1-2-phase excitation				θ = 8/16	66	71	76	
		—				θ = 9/16	58	63	68	
		2W1-2-phase excitation				θ = 10/16	51	56	61	
		—				θ = 11/16	42	47	52	
		2W1-2-phase excitation				θ = 12/16	33	38	43	
		—				θ = 13/16	24	29	34	
		—				θ = 14/16	15	20	25	
—	θ = 15/16	5	10	15						
2-phase excitation		—	—	—	—	100	—	—		
Reference voltage		VNF	—	TQ1, TQ2 = L (100%) OSC = 100 kHz	450	500	550	mV		
Output transistor switching characteristics		tr	7	RL = 2 Ω, VNF = 0 V, CL = 15 pF	—	0.1	—	μs		
		tf			—	0.1	—			
Delay time		tpLH	7	ENABLE to output	—	0.1	—	μs		
		tpLH			—	0.3	—			
		tpHL			—	0.2	—			
Output leakage current	Upper side	ILH	6	VM = 40 V	—	—	1	μA		
	Lower side	ILL			—	—	1			

Note: Maximum current (θ = 0): 100%

## Description of Functions

### 1. Excitation Settings

You can use the M1 and M2 pin settings to configure four different excitation settings. (The default is 2-phase excitation using the internal pull-down.)

Input		Mode (Excitation)
M2	M1	
L	L	2-phase
L	H	1-2-phase
H	L	4W1-2-phase
H	H	2W1-2-phase

### 2. Function

You can change the output to OFF and Initial mode by using the ENABLE and  $\overline{\text{RESET}}$  pins respectively.

In Initial mode, the CLK and CW/CCW settings don't matter.

Input				Output Mode
CLK	CW/CCW	$\overline{\text{RESET}}$	ENABLE	
	L	H	H	CW
	H	H	H	CCW
X	X	L	H	Initial mode
X	X	X	L	Z

X: Don't care

### 3. Initial Mode

When  $\overline{\text{RESET}}$  is used, the phase currents are as follows. In this instance, the MO pin is L (connected to open drain).

Excitation Mode	A Phase Current	B Phase Current
2-phase	100%	-100%
1-2-phase	100%	0%
W1-2-phase	100%	0%
2W1-2-phase	100%	0%

**4. Current Decay Settings**

Output is generated by four PWM blasts; 25% decay is created by inducing decay during the last blast in Fast mode; 50% decay is created by inducing decay during the last two blasts in Fast mode; and 100% decay is created by inducing all four blasts in Fast mode.

If there is no input with the pull-down resistor connection then the setting is Normal.

Dcy2	Dcy1	Current Decay Setting
L	L	Normal 0%
L	H	25% Decay
H	L	50% Decay
H	H	100% Decay

**5. Torque Settings (Current Value)**

The current ratio used in actual operations is determined in regard to the current setting due to resistance. Configure this for extremely low torque scenarios such as when Weak Excitation mode is stopped.

If there is no input with the pull-down resistor connection then the setting is 100% torque.

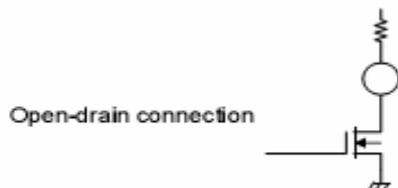
TQ2	TQ1	Current Ratio
L	L	100%
L	H	75%
H	L	50%
H	H	20% (weak excitation)

**6. Protect and MO (Output Pins)**

You can configure settings from the receiving side by using an open drain connection for the output pins and making the pull-up voltage variable.

When a given pin is in its designated state it will go ON and output at Low level.

Pin State	Protect	MO
Low	Overheat protection operation	Initial state
Z	Normal operation	Other than initial state



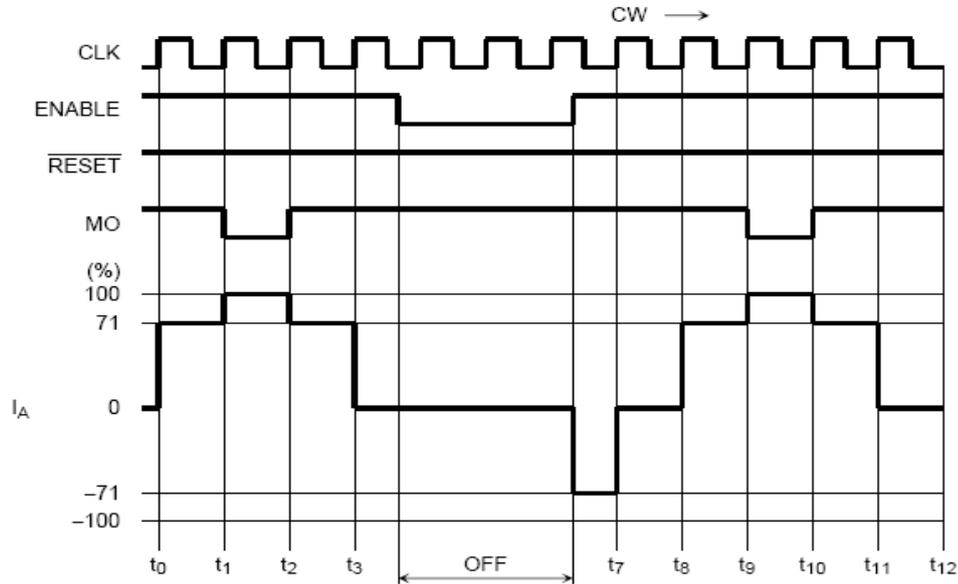
**7. OSC**

Output chopping waves are generated by connecting the condenser and having the CR oscillate.  
The values are as shown below (roughly:  $\pm 30\%$  margin of error).

Condenser	Oscillating Frequency
1000 pF	44 kHz
330 pF	130 kHz
100 pF	400 kHz

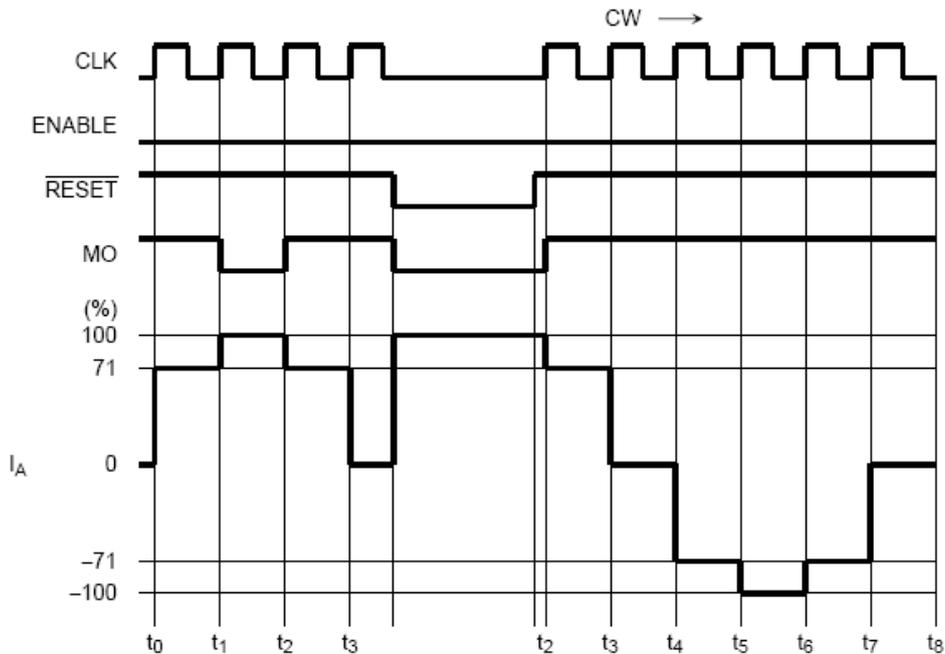
Relationship between Enable,  $\overline{\text{RESET}}$  and Output (OUT and MO)

Ex-1: ENABLE 1-2-Phase Excitation (M1: H, M2: L)



The ENABLE signal at Low level disables only the output signals. Internal logic functions proceed in accordance with input clock signals and without regard to the ENABLE signal. Therefore output current is initiated by the timing of the internal logic circuit after release of disable mode.

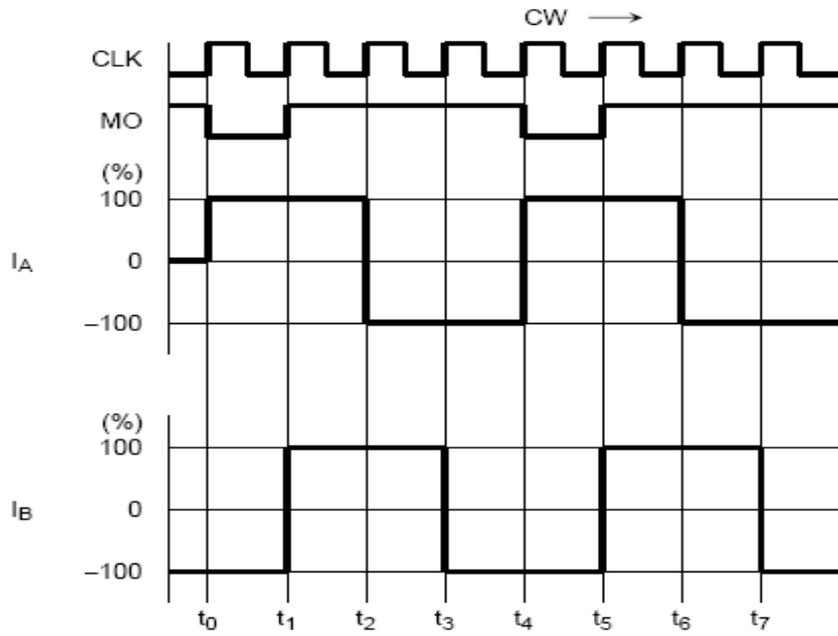
Ex-2:  $\overline{\text{RESET}}$  1-2-Phase Excitation (M1: H, M2: L)



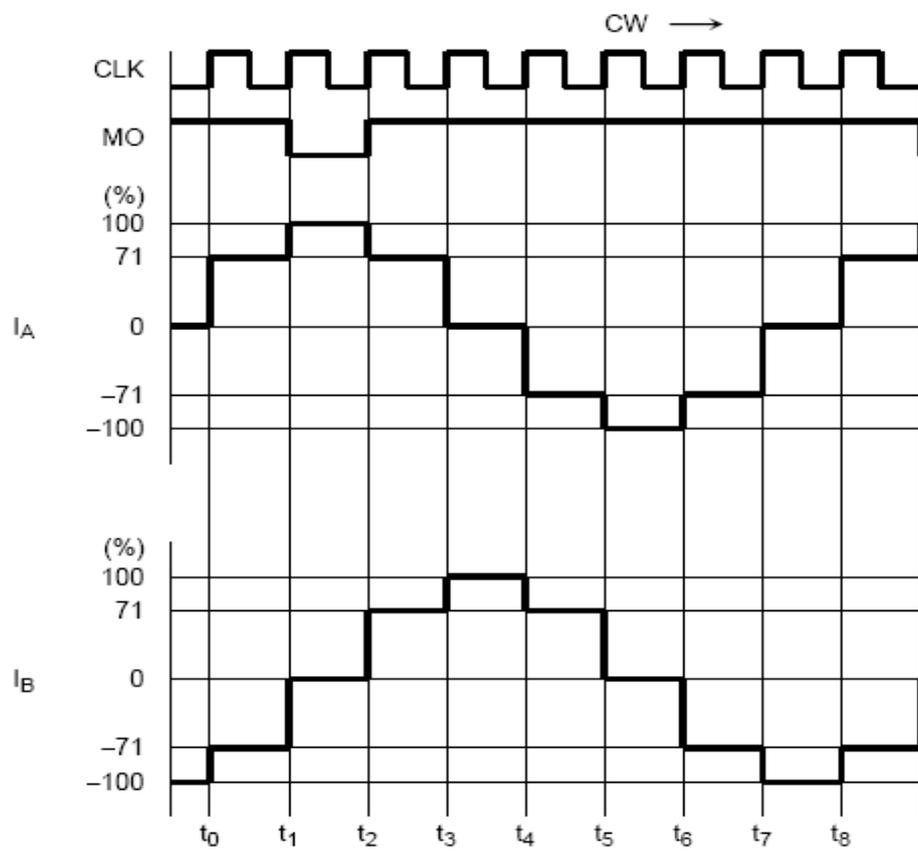
When the  $\overline{\text{RESET}}$  signal goes Low level, output goes Initial state and the MO output goes Low level (Initial state: A Channel output current is 100%).

Once the  $\overline{\text{RESET}}$  signal returns to High level, output continues from the next state after Initial from the next raise in the Clock signal.

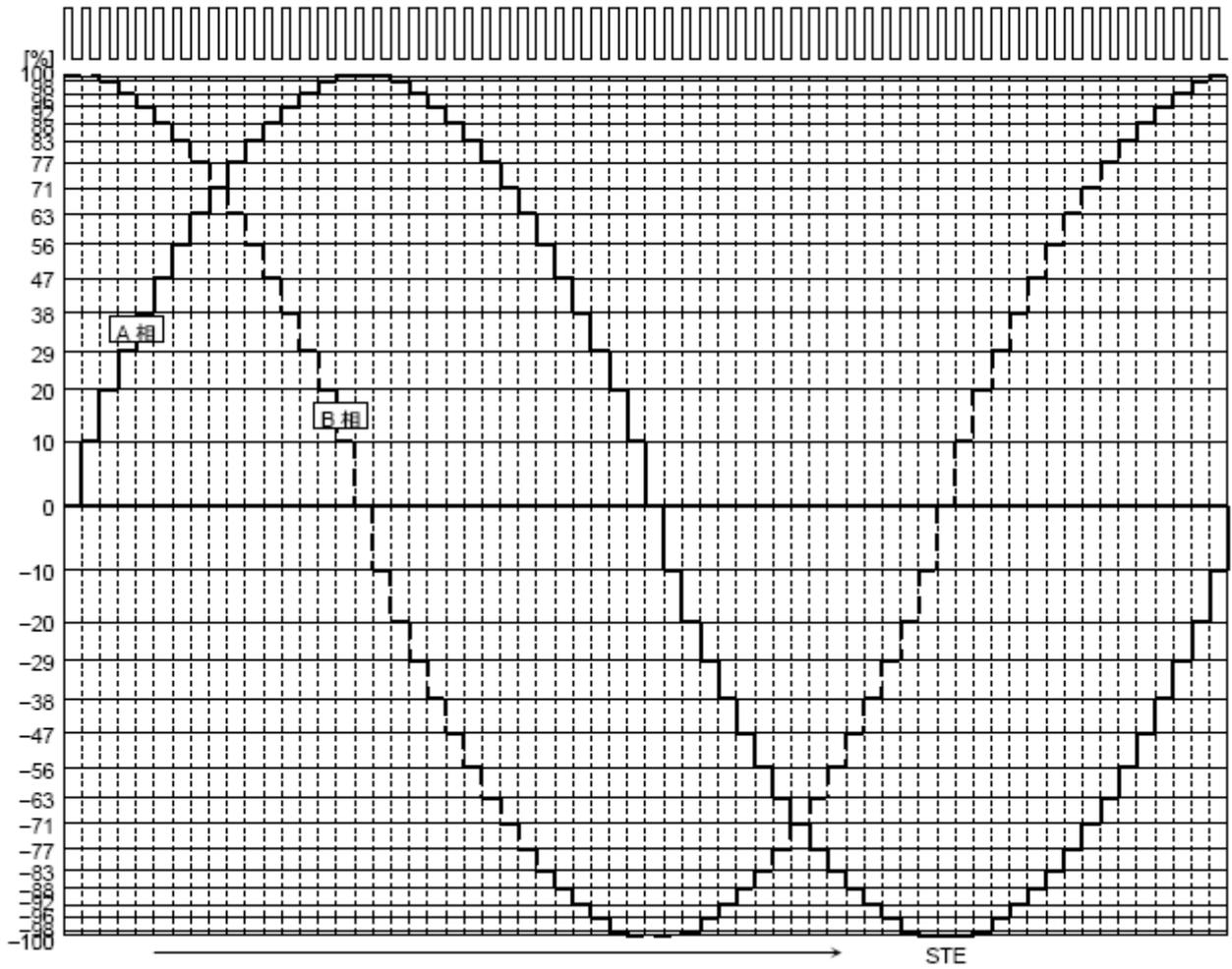
2-Phase Excitation (M1: L, M2: L, CW Mode)



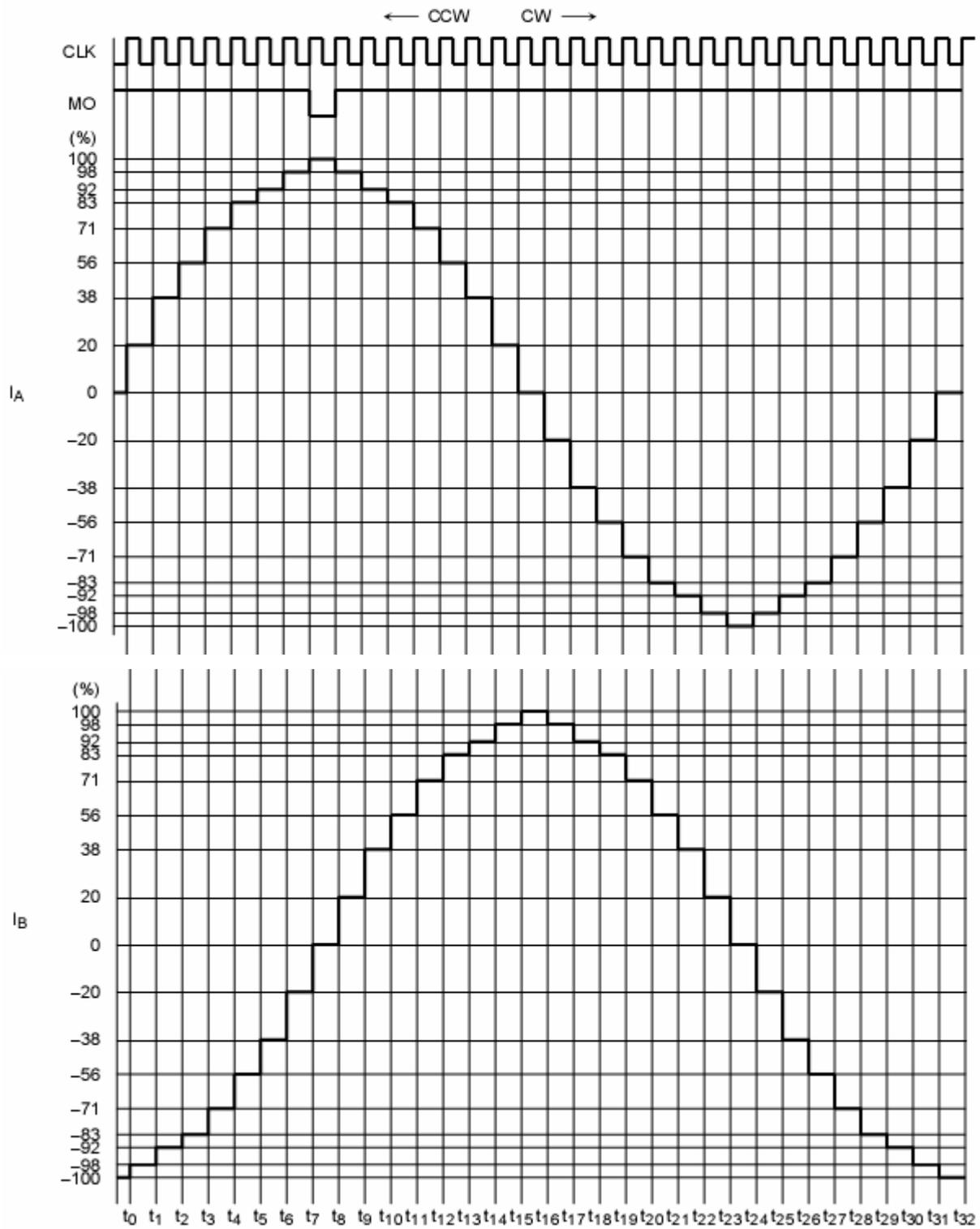
1-2-Phase Excitation (M1: H, M2: L, CW Mode)



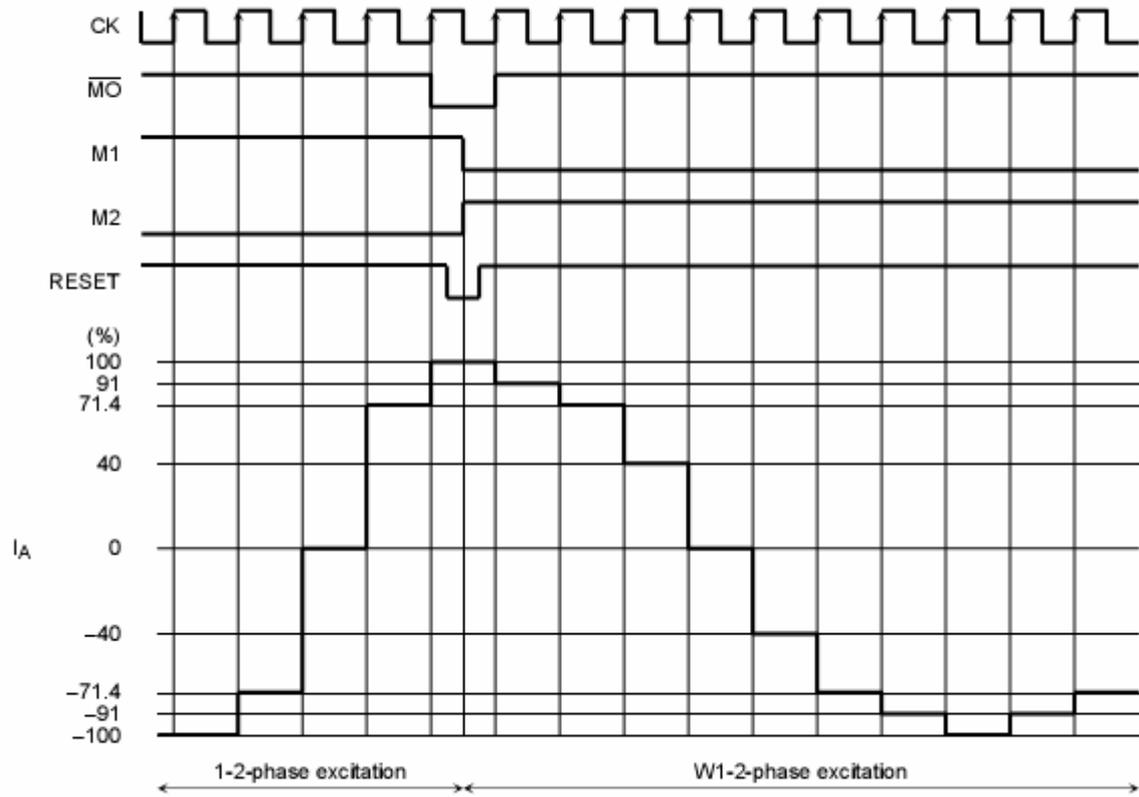
4W1-2-Phase Excitation (M1: L, M2: H, CW Mode)



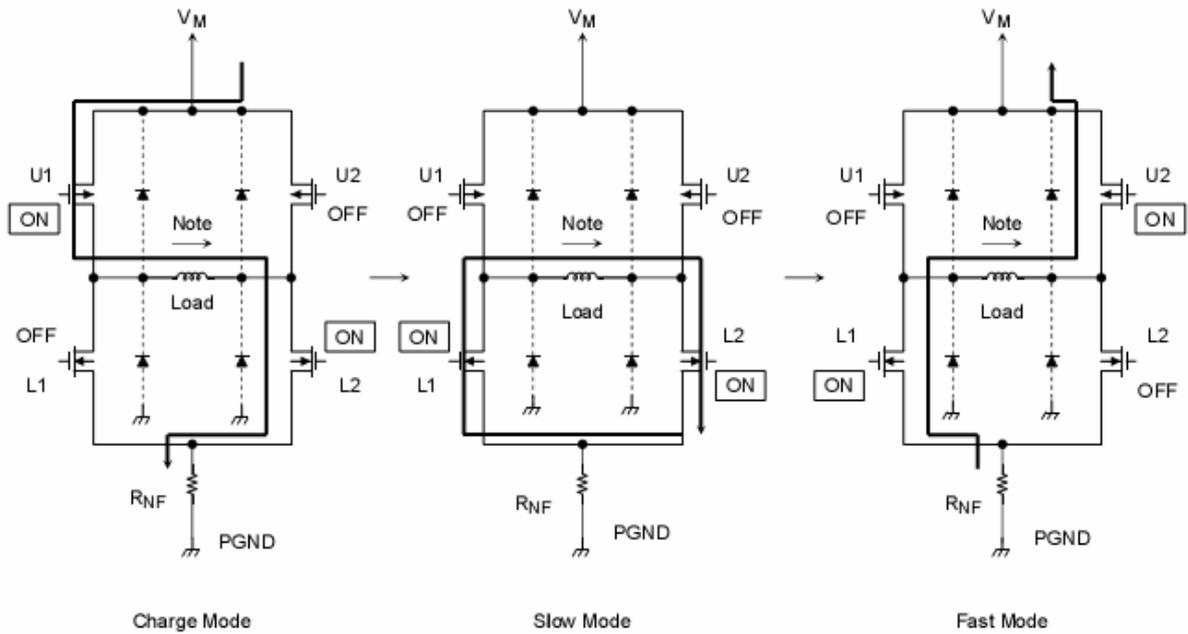
2W1-2-Phase Excitation (M1: H, M2: H, CW Mode)



<Input Signal Example>



Output Stage Transistor Operation Mode



Output Stage Transistor Operation Functions

CLK	U1	U2	L1	L2
CHARGE	ON	OFF	OFF	ON
SLOW	OFF	OFF	ON	ON
FAST	OFF	ON	ON	OFF

Note: The above chart shows an example of when the current flows as indicated by the arrows in the above figures. If the current flows in the opposite direction, refer to the following chart:

CLK	U1	U2	L1	L2
CHARGE	OFF	ON	ON	OFF
SLOW	OFF	OFF	ON	ON
FAST	ON	OFF	OFF	ON

**1. How to Turn on the Power**

Turn on VDD. When the voltage has stabilized, turn on VMA/B.

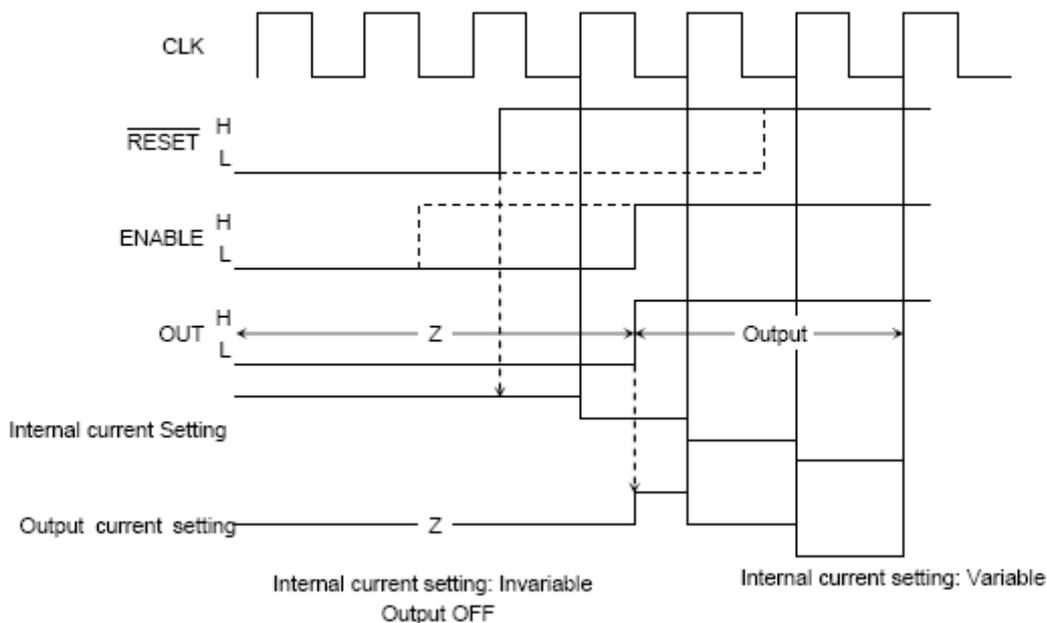
In addition, set the Control Input pins to Low when inputting the power.

(All the Control Input pins are pulled down internally.)

Once the power is on, the CLK signal is received and excitation advances when RESET goes high and excitation is output when ENABLE goes high. If only RESET goes high, excitation won't be output and only the internal counter will advance. Likewise, if only ENABLE goes high, excitation won't advance even if the CLK signal is input and it will remain in the initial state.

The following is an example:

<Recommended Control Input Sequence>



**2. Calculating the Setting Current**

To perform constant-current operations, it is necessary to configure the base current using an external resistor. If the voltage on the NFA (B) pin is 0.5 V (with a torque of 100%) or greater, it will not charge.

Ex.: If the maximum current value is 1 A, the external resistance will be 0.5 W.

**3. PWM Oscillator Frequency (External Condenser Setting)**

An external condenser connected to the OSC pin is used to internally generate a saw tooth waveform. PWM is controlled using this frequency. Toshiba recommends 100 to 3300 pF for the capacitance, taking variations between ICs into consideration.

Approximation:  $f_{osc} = 1 / (C_{osc} * 1.5 * (10 / C_{osc} + 1) / 66) * 1000 \text{kHz}$

**4. Power Dissipation**

The IC power dissipation is determined by the following equation :

$$P=V_{DD} \cdot I_{OUT} \cdot R_{on} \cdot 2 \text{drivers}$$

The higher the ambient temperature, the smaller the power dissipation.

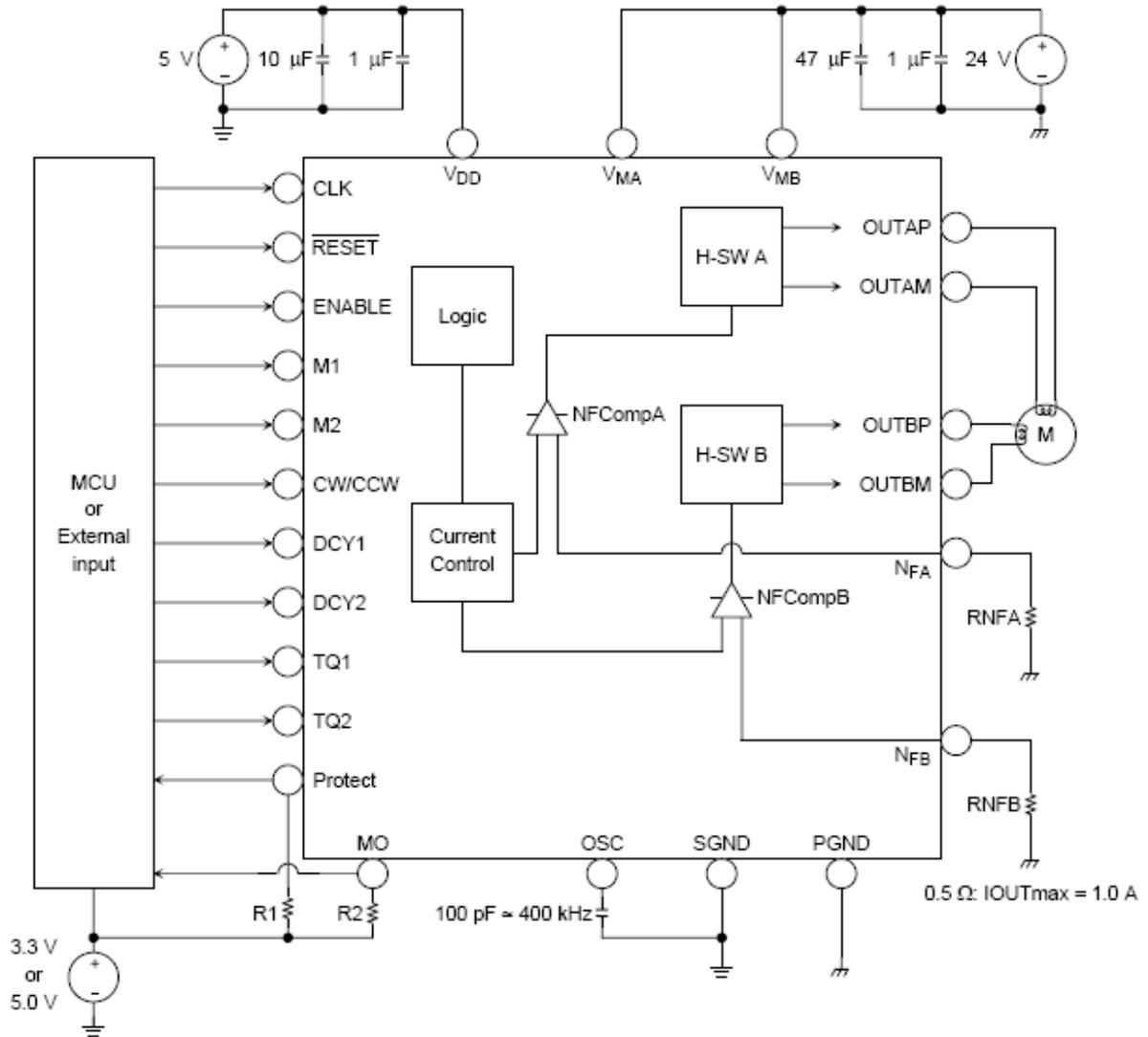
Check the PD-Ta curve, and be sure to design the heat dissipation with a sufficient margin.

**5. Heat Sink Fin Processing**

The IC fin (rear) is electrically connected to the rear of the chip. If current flows to the fin, the IC will malfunction. If there is any possibility of a voltage being generated between the IC GND and the fin, either ground the fin or insulate it.

**6. Thermal Protection**

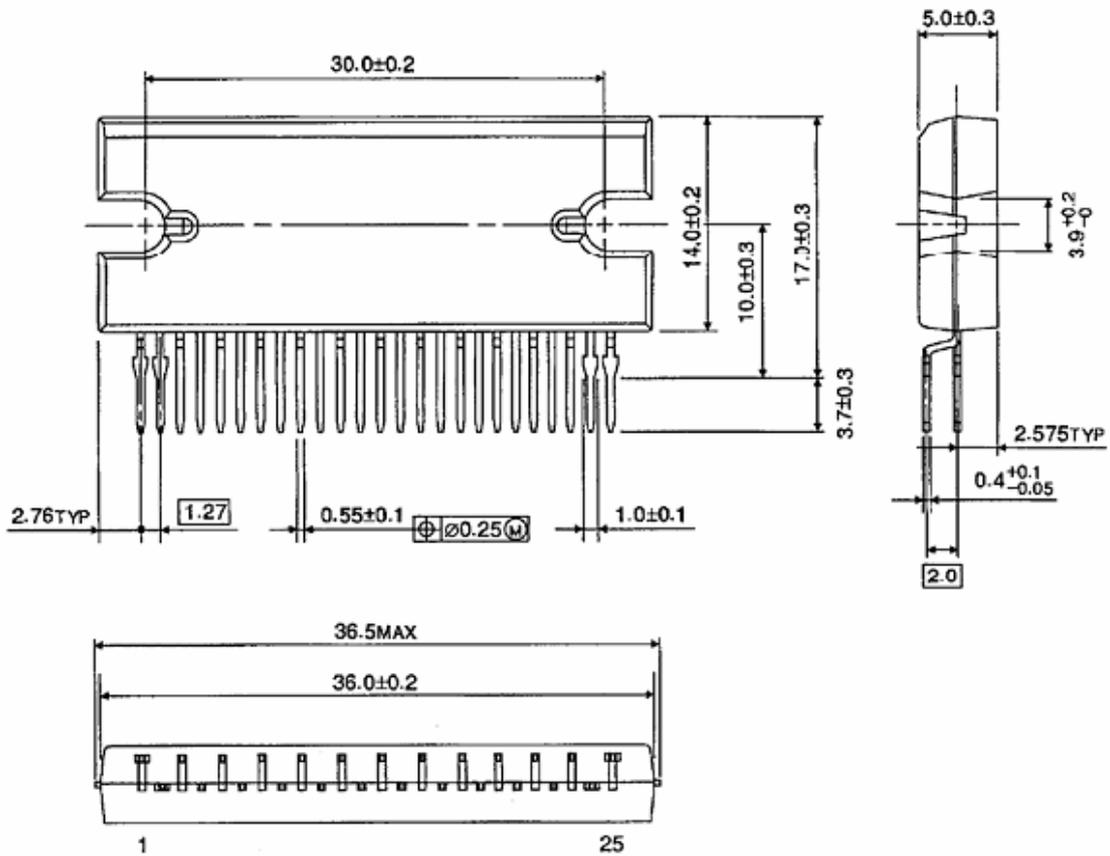
When the temperature reaches 170°C (as standard value), the thermal protection circuit is activated switching the output to off. There is a variation of plus or minus about 20 C in the temperature that triggers the circuit operation.



Package Dimensions

HZIP25-P-1.27

Unit : mm



Weight: 9.86 g (typ.)